

Modeling Fluid-Structure Interaction of Biodegradation in Engineered Tissue Scaffolds

Priyanka Patki
Francesco Costanzo

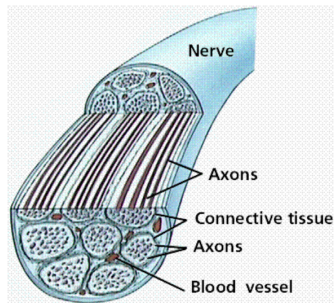
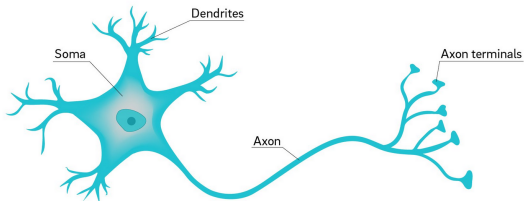


Overview

- 1 Introduction
 - Physical Problem
- 2 Modelling of degrading porous scaffolds
 - Mass balance
 - Momentum balance
- 3 COMSOL Implementation
- 4 Closing remarks

Introduction

Neurons and nerves



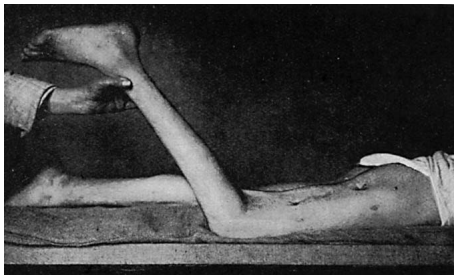
- A neuron ¹
- Carries messages brain ↔ body

- Cross section of a nerve ²
- Bundle of axons

¹https://ucsdnews.ucsd.edu/pressrelease/why_are_neuron_axons_long_and_spindly

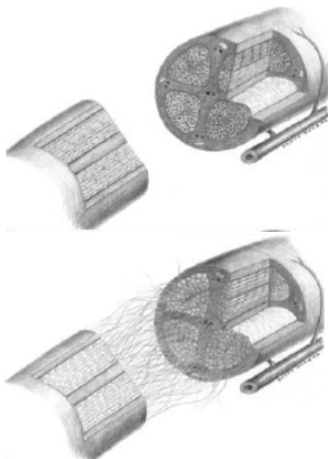
²Purves *et al.*, Life: The Science of Biology, 4th Edition

Nerve injuries



¹Zochodne, Douglas W. Neurobiology of peripheral nerve regeneration. Cambridge, UK: Cambridge University Press, 2008

Nerve injuries

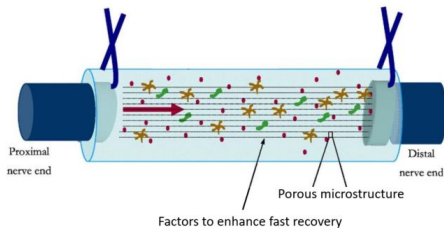


- Loss of sensation or motor control
- Large gap: Mis-alignment of regrowing fibres

¹Zochodne, Douglas W. Neurobiology of peripheral nerve regeneration. Cambridge, UK: Cambridge University Press, 2008

Tissue Engineered Nerve Guidance Channels

A typical nerve regeneration scaffold ¹



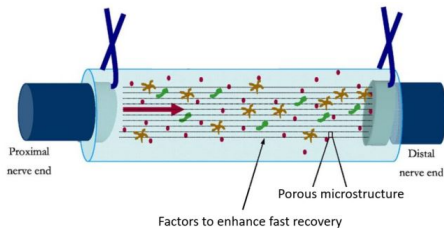
- Biocompatible
- Porous
- Mechanical strength
- Biodegradable

Chemo-mechanical coupling

¹Bellamkonda, R.V., Biomaterials, 27(19):3515-3518, 2006.

Tissue Engineered Nerve Guidance Channels

A typical nerve regeneration scaffold ¹



Components:

- Porous degrading solid
- Base fluid
- Product of degradation (Monomer)

Reactive Fluid-Structure Interaction (FSI)

¹Bellamkonda, R.V., *Biomaterials*, 27(19):3515-3518, 2006.

Modelling of degrading porous scaffolds

Incompressibility, Saturation and Mass balance:

- Mixture theory

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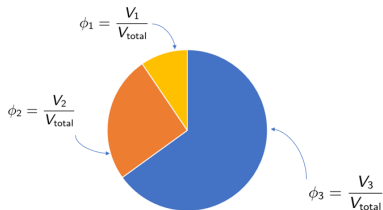
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Incompressibility, Saturation and Mass balance:

- Mixture theory
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$$\frac{\partial \rho_a}{\partial t} + \nabla \cdot (\rho_a \mathbf{v}_a) = \hat{c}_a$$

- Saturation condition: $\sum_{a=1}^N \phi_a = 1$



Momentum balance

After deriving constitutive relationships, we get:

- Balance of momentum - solid

$$-\nabla \cdot \mathbf{T}^e - \rho_s \mathbf{b}_s + \phi_s \nabla p - \phi_1^2 \frac{\mu_1}{\kappa_s} (\mathbf{v}_1 - \mathbf{v}_s) - \phi_2^2 \frac{\mu_2}{\kappa_s} (\mathbf{v}_2 - \mathbf{v}_s) = \mathbf{0},$$

- Balance of momentum - fluid (f=1,2)

$$-\rho_f \mathbf{b}_f + \phi_f \nabla p + \phi_f^2 \frac{\mu_f}{\kappa_s} (\mathbf{v}_f - \mathbf{v}_s) = \mathbf{0},$$

- Fluid-Solid interaction: Non-linear, Darcy flow-like term
 - μ_f : viscosity of fluid
 - κ_s : permeability of porous solid
- Non-linear PDEs

COMSOL Implementation

FEM Implementation

For our 3-component system, we have

FEM Implementation

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- 8 variables...
 - Three velocities: \mathbf{v}_s , \mathbf{v}_1 , \mathbf{v}_2
 - Solid displacement: \mathbf{u}_s
 - Volume fractions: ϕ_s , ϕ_1 , ϕ_2
 - Pressure: p

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 - Co-ordinate frame follows solid

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Eulerian strong form

→ ALE strong form

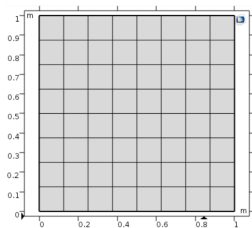
→ ALE weak form

→ Descretized weak form → COMSOL Multiphysics

COMSOL Implementation

COMSOL Multiphysics → Mathematics Module → Weak form PDE

Choice of finite elements



- Square domain, side = 1 m.
- Discretized into square cells
- "Swept mesh": element size = $\frac{1}{h}$ m.

- Lagrange polynomial interpolation for all variables
- In order to satisfy the *inf-sup* or *Brezzi-Babuska* condition:
 - Degree of interpolation of scalars is one less than that of vectors:
 - Lagrange quadratic elements for vectors, linear for scalars
 - Lagrange cubic and quadratic elements for vectors and scalars respectively.

Numerical Scheme - Method of Manufactured Solutions

- FEM implementation tested using Method of Manufactured Solutions:
 - 1 Impose a known solution for all variables
 - 2 Derive force fields and boundary conditions
 - 3 Solve the problem and compare solution with the imposed manufactured solution
- Basically, we check if our numerical scheme gives us correct solutions of a problem with known solutions

Numerical Scheme - Method of Manufactured Solutions

- Example: Velocity of fluid

- 1 Imposed 'Solution' - radially varying sinusoidal function:

$$v_x = v_0 \cos\left(2\pi \frac{t}{t_0}\right) \sin\left(2\pi \frac{x^2+y^2}{L^2}\right)$$

- 2 Derive force fields and boundary conditions by substituting into governing equations
- 3 Solve the problem to obtain manufactured solution:

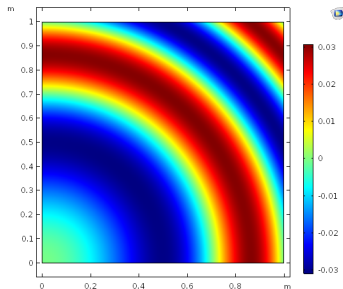
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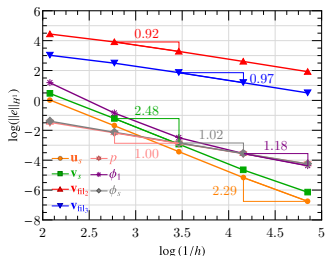
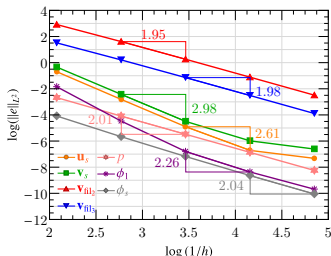
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Convergence analysis

- Convergence analysis carried out by performing parametric sweep over mesh size: $h = 1/8, 1/16, 1/32, 1/64, 1/128m$
- Postprocessing: “Global integration” feature
 - L^2 error norm: $\log(\|e\|_{L^2}) = \frac{\|a_{sol} - a_{MS}\|}{\|a_{MS}\|}$
 - H^1 error semi-norm: $\log(\|e\|_{H^1}) = \frac{\|\nabla a_{sol} - \nabla a_{MS}\|}{\|\nabla a_{MS}\|}$



Convergence rates when quadratic elements for vectors and linear elements for scalars are used.

Closing remarks

Closing remarks

- Summary
 - Mixture theoretic model to study chemistry-mechanical property evolution of degrading scaffolds developed
 - COMSOL implementation of the FEM model tested using Method of Manufactured Solutions for stability and accuracy
- Ongoing and future work
 - Experimental validation of numerical model for degradation mechanisms of actual TENG materials
- We gratefully acknowledge the support by the National Science Foundation grants CMMI 1537008 and CBET 1705854.



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Appendix

Parameter	Value
m_s	$3e3kg/ms^2$
μ_2	$1e-3kg/sm$
μ_3	$1.5e-3kg/sm$
κ_s	$1e-3m^2$

$$\mathbf{u}_s = \bar{u}_s \sin\left(\frac{2\pi t}{t_0}\right) \left[\cos\left(2\pi \frac{x+y}{L}\right) \mathbf{i} + \sin\left(2\pi \frac{x-y}{L}\right) \mathbf{j} \right], \quad (1)$$

$$\mathbf{v}_{\text{fil}_2} = \bar{v}_{\text{fil}_2} \cos\left(\frac{2\pi t}{t_0}\right) \left[\sin\left(2\pi \frac{x^2+y^2}{L^2}\right) \mathbf{i} + \cos\left(2\pi \frac{x^2-y^2}{L^2}\right) \mathbf{j} \right], \quad (2)$$

$$\mathbf{v}_{\text{fil}_3} = \bar{v}_{\text{fil}_3} \cos\left(\frac{2\pi t}{t_0}\right) \left[\cos\left(2\pi \frac{x^2}{L^2}\right) \sin\left(2\pi \frac{y^2}{L^2}\right) \mathbf{i} + \sin\left(2\pi \frac{x^2-y^2}{L^2}\right) \mathbf{j} \right], \quad (3)$$

$$p = \bar{p} \sin\left(\frac{2\pi t}{t_0}\right) \sin\left(2\pi \frac{x+y}{L}\right), \quad (4)$$

$$\phi_2 = \check{\phi}_2 + \bar{\phi}_2 \cos\left(\frac{2\pi t}{t_0}\right) \cos\left(2\pi \frac{x+y}{L}\right), \quad (5)$$

$$\phi_s = \check{\phi}_s + \bar{\phi}_s \sin\left(\frac{2\pi t}{t_0}\right) \sin\left(2\pi \frac{x+y}{L}\right), \quad (6)$$

Constant	Value
\bar{u}_s	$0.001m$
\bar{v}_{fil_1}	$0.1m/s$
\bar{v}_{fil_2}	$0.1m/s$
\bar{p}	$1Pa$

Constitutive Relations for $\hat{\mathbf{p}}_a$ and \mathbf{T}_a

- Mass balance:

$$\frac{\partial \phi_a}{\partial t} + \nabla \cdot (\phi_a \mathbf{v}_a) = \frac{\hat{c}_a}{\gamma_a}$$

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- Second law of thermodynamics:

$$-\sum_{a=1}^N \dot{\Psi}_a - \sum_{a=1}^N \text{tr}((\Psi_a \mathbf{I} - \mathbf{T}_a^T) \nabla \mathbf{v}_a) - \sum_{a=1}^N (\hat{\mathbf{p}}_a + \frac{1}{2} \hat{c}_a (\mathbf{v}_a - \mathbf{v}_1)) \cdot (\mathbf{v}_a - \mathbf{v}_1) \geq 0,$$

- $(\hat{\mathbf{p}}_a, \mathbf{T}_a, \Psi_a)$ are assumed to be functions of $(C_s, \phi_a, \mathbf{v}_a)$ and their gradients

Constitutive Relations for $\hat{\mathbf{p}}_a$ and \mathbf{T}_a

- Combining the two, we get a 'Variational inequality' and a Lagrange multiplier, P ,

$$\begin{aligned}
 & - \sum_{a=1}^N \dot{\Psi}_a - \sum_{a=1}^N \text{tr}((\Psi_a \mathbf{I} - \mathbf{T}_a^T) \nabla \mathbf{v}_a) - \sum_{a=1}^N (\hat{\mathbf{p}}_a + \frac{1}{2} \hat{\mathbf{c}}_a (\mathbf{v}_a - \mathbf{v}_1)) \cdot (\mathbf{v}_a - \mathbf{v}_1) \\
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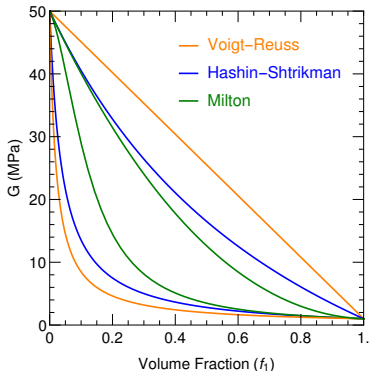
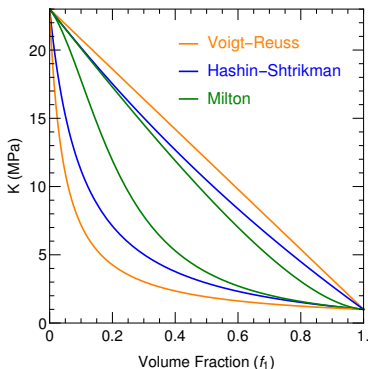
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- Substituting the constitutive assumptions and solving the variational inequality, we get,
 - Constitutive relations for \mathbf{T}_a and $\hat{\mathbf{p}}_a$
 - P , the Lagrange multiplier, represents the 'base' pressure in the system.

Elastic properties

($K_1 = 1 \text{ MPa}$, $K_2 = 23 \text{ MPa}$, $G_1 = 1 \text{ MPa}$ and $G_2 = 50 \text{ MPa}$)



¹Voigt, L., Lehrbuch der Kristallphysik. (mit Ausschluss der Kristalloptik), 1910

²Reuss, A., ZAMM - Journal of Applied Mathematics and Mechanics, 9(1):49-58, 1929

³Hashin *et al.*, Journal of the Mechanics and Physics of Solids, 10(4):343-352, 1962

⁴Milton, G. W., Physical Review Letters, 46(8):542-545, 1981

Transport properties

- **Effective diffusion coefficient¹**
Brownian motion of fluid particles hindered by porous structure

- Hashin-Shtrikman (Volume fraction only)

$$\frac{D_e}{D_1} = \frac{2}{2 + f_2},$$

- Ogston - low density approximation (Volume fraction only)

$$\frac{D_e}{D_1} = 1 - \frac{2}{3}f_2,$$

- Torquato approximation (S_2 and higher order functions)

$$\frac{D_e}{D_1} = \frac{1}{1 - f_2} \frac{(1 + \frac{1}{2}\frac{\gamma_2}{\xi_2} - \frac{1}{2}\xi_2) + (-1 + \frac{1}{2}\frac{\gamma_2}{\xi_2} - \frac{1}{2}\xi_2)f_2}{(1 + \frac{1}{2}\frac{\gamma_2}{\xi_2} - \frac{1}{2}\xi_2) + (\frac{1}{2} + \frac{1}{2}\frac{\gamma_2}{\xi_2} + \frac{1}{4}\xi_2)f_2}$$

- f_2 - Volume fraction of solid phase
- ξ_i, γ_i - parameters derived using $S_2, S_3, S - 4$

¹Jiao *et al.*, *Physical Biology*, 9(3):1-13, 2012