

Vibration and Acoustic Analysis of Trussed Railroad Bridge under Moving Loads

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Outline & Introduction

- Motivation
 - Denied Area Monitoring
 - Structural Health Monitoring
 - Battle damage assessment
- Structural Finite Element Model
 - Railroad bridge at Ft. Leonard Wood, MO
 - Transient response of structure due to vehicle loading
 - Brief description of implementation of moving load representation
 - Predict response due to different loadings
 - Axle speed
 - Axle weight
 - Single axle vs. Multiple axles (locomotive)
 - Model does not include effects of vehicle suspension
- Acoustic Finite Element Model
 - Include topography with ground impedance
 - Outputs of structural model used as inputs to acoustic model
 - Predict SPL (single axle)
 - Different frequency components
 - Different loading conditions
- Summary & Conclusions



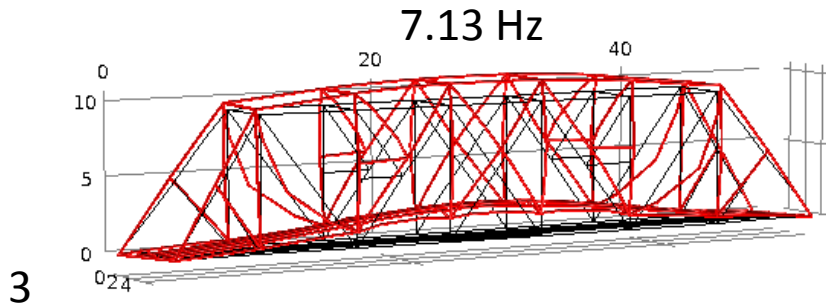
Motivation

STRUCTURAL HEALTH MONITORING

- Battle Damage Assessment
- Remote assessment of structures for route reconnaissance
 - To complement satellite imagery
 - Scour usually not visible
- Significant changes in frequency response could indicate bridge instability

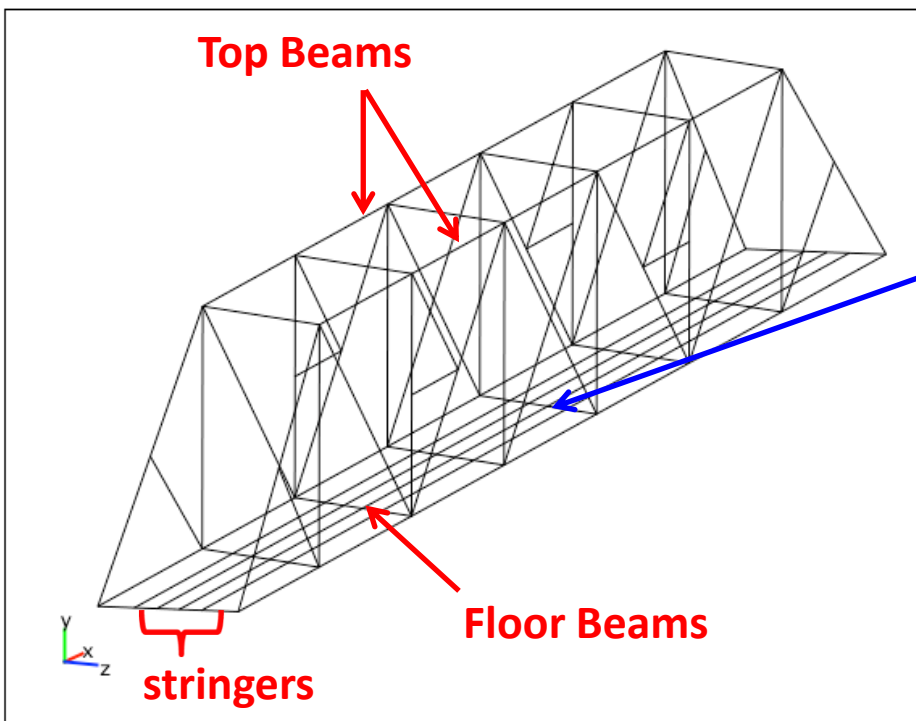
REMOTE TRAFFIC MONITORING

- Determine changes in traffic patterns
- Number and weight of vehicles
- Speed of travel



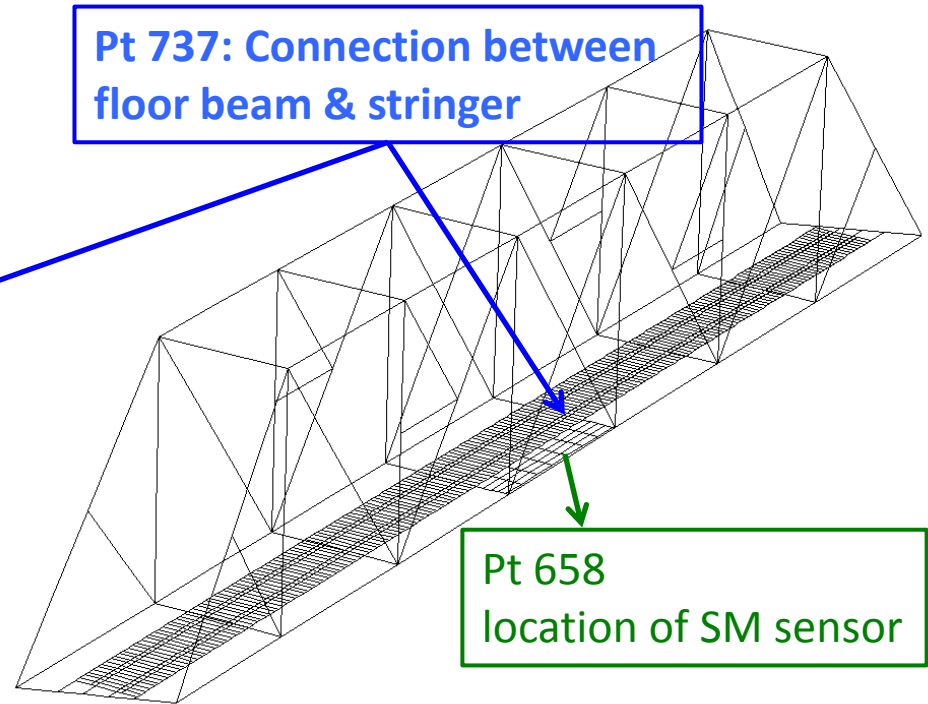
Structural Model

Anatomy of Ft. Leonard Wood Bridge



Truss bridge model

- 7 panel bridge
- 25° skew angle at ends of bridge
- Pinned at each end
- 3D Euler Beam elements
 - Material properties: E , ρ , ν
 - Cross section properties: A , I_{yy} , I_{zz}



Model with cross-ties & rails

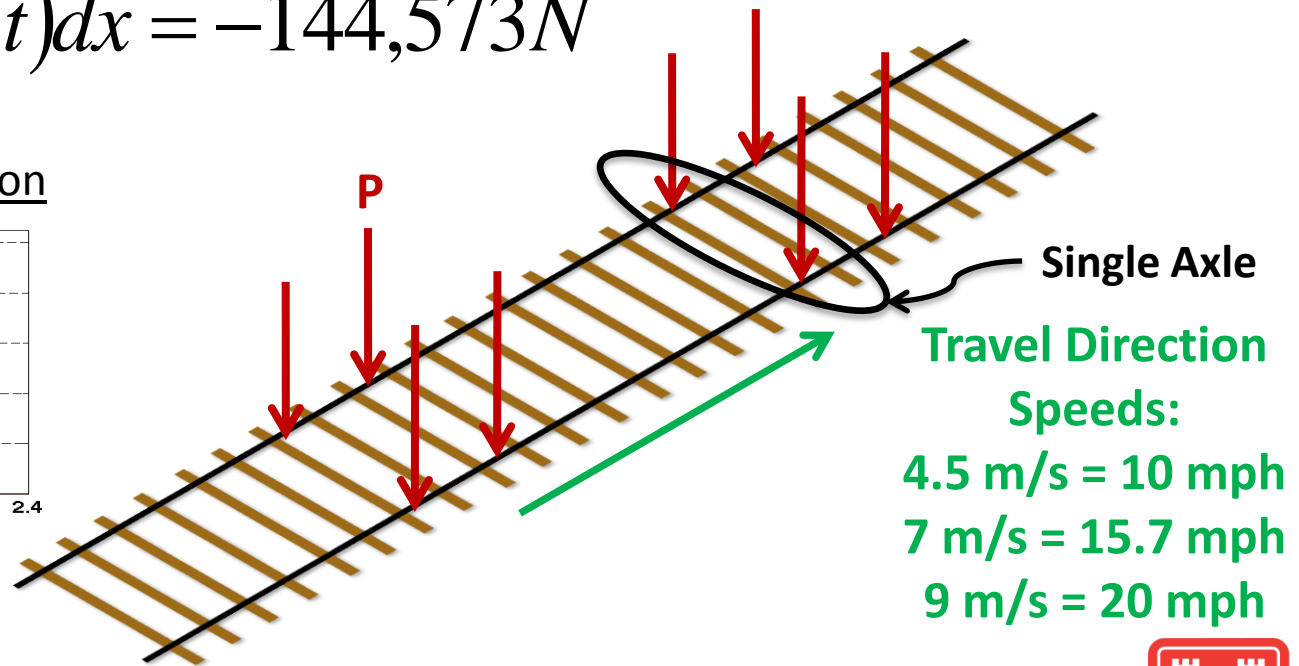
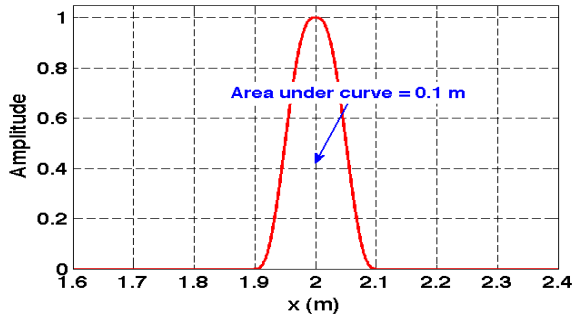
- Transmits load to structure
- Connections between crossties & stringers
 - Pinned – allows for more movement
 - Clamped – stiffer

Traveling Load: Single Axle

- Single axle model
 - 2 wheels traveling across bridge at constant speed
 - Makes interpretation easier
- Locomotive model
 - Superposition of 4 single axle models with delays representing wheel spacings
- Traveling load distribution function represents concentrated load from each wheel
 - Verified formulation by calculating moving force on Euler Beams

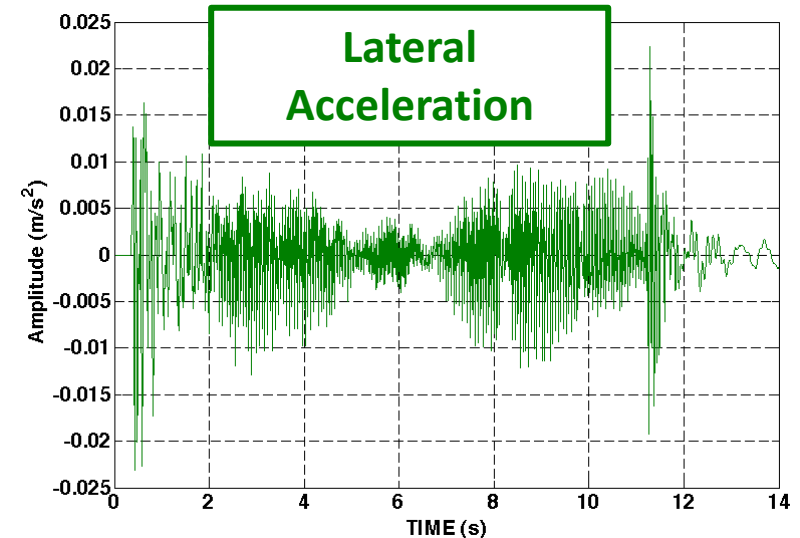
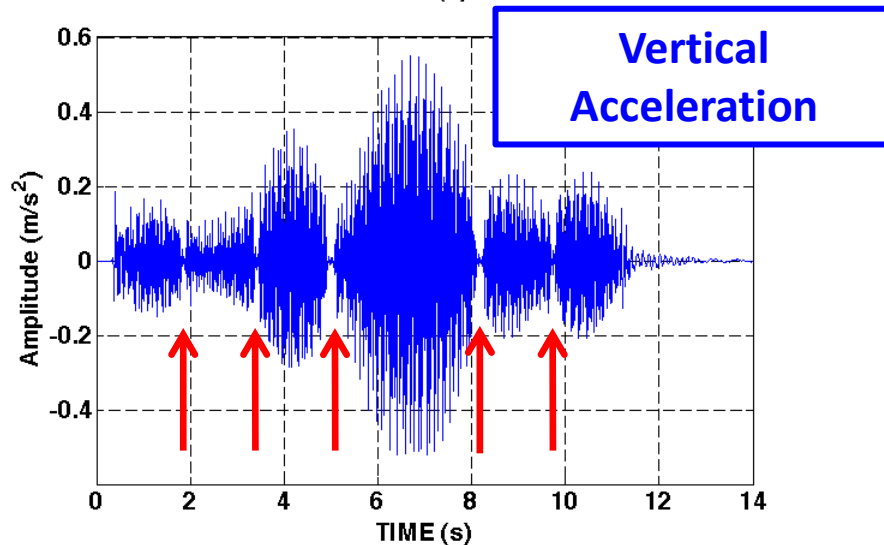
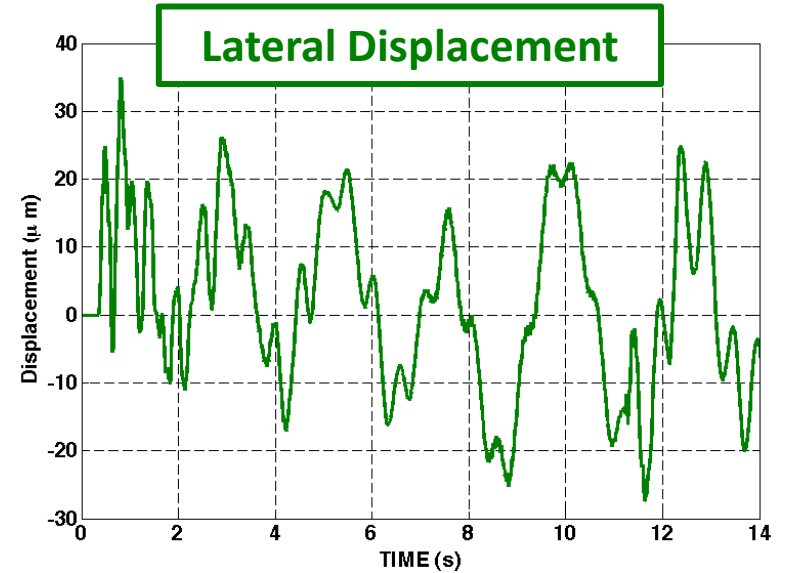
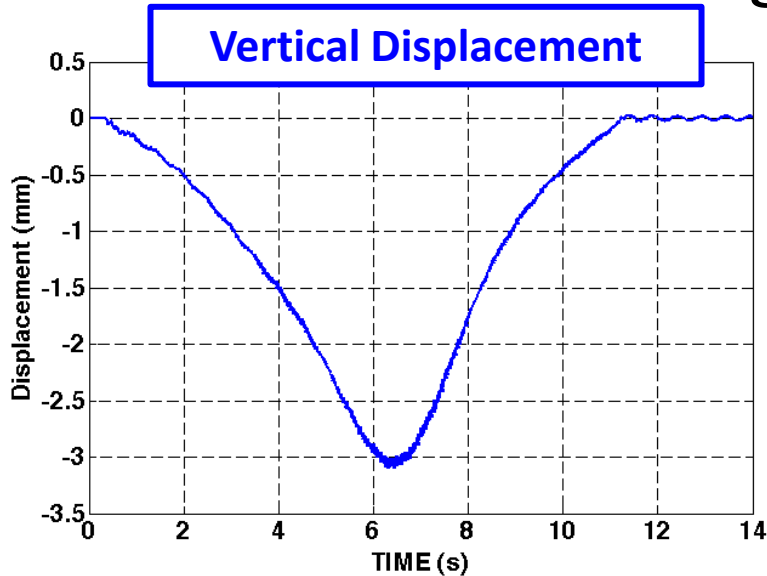
$$P = \int F_0 \delta(x - vt) dx = -144,573 N$$

Load Distribution Function



FE Results at Point 737

1 axle traveling at 10 mph (4.5 m/s)



6

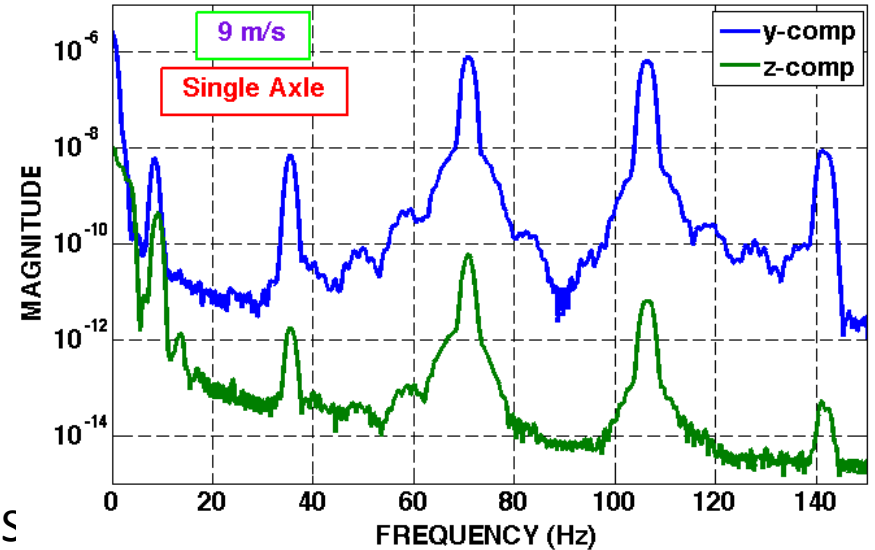
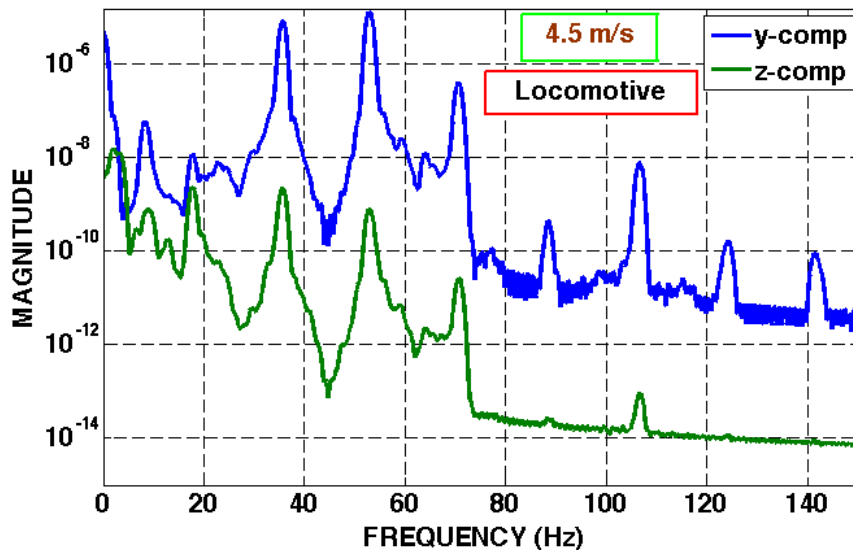
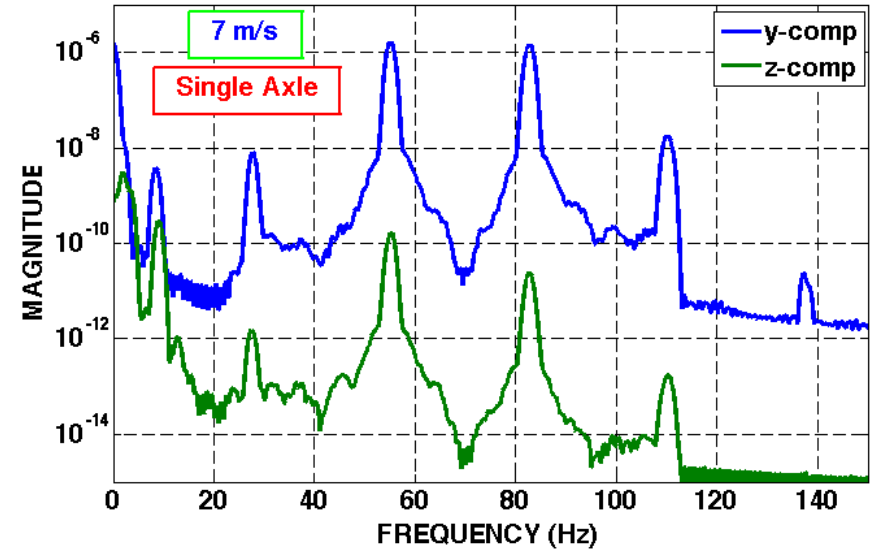
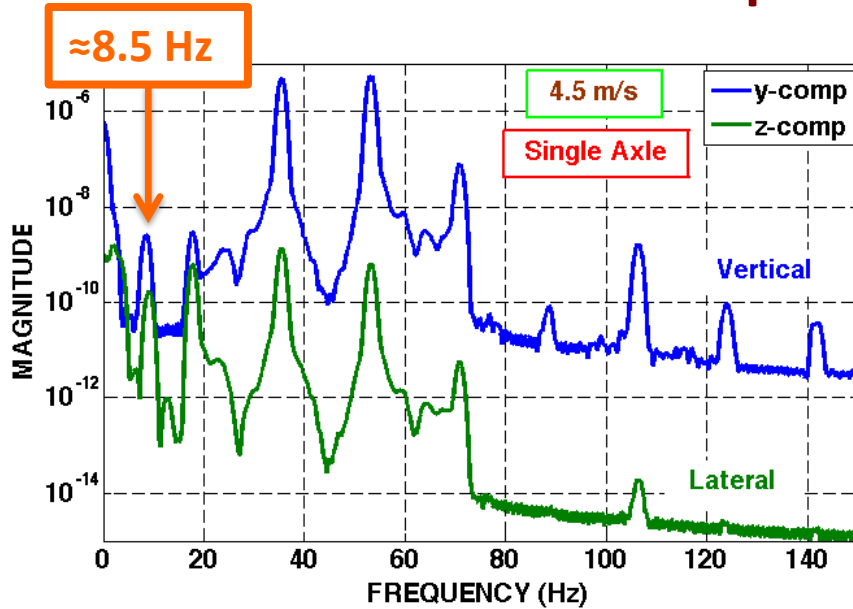
wheels crossing floor beams

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Power Spectra: Point 737

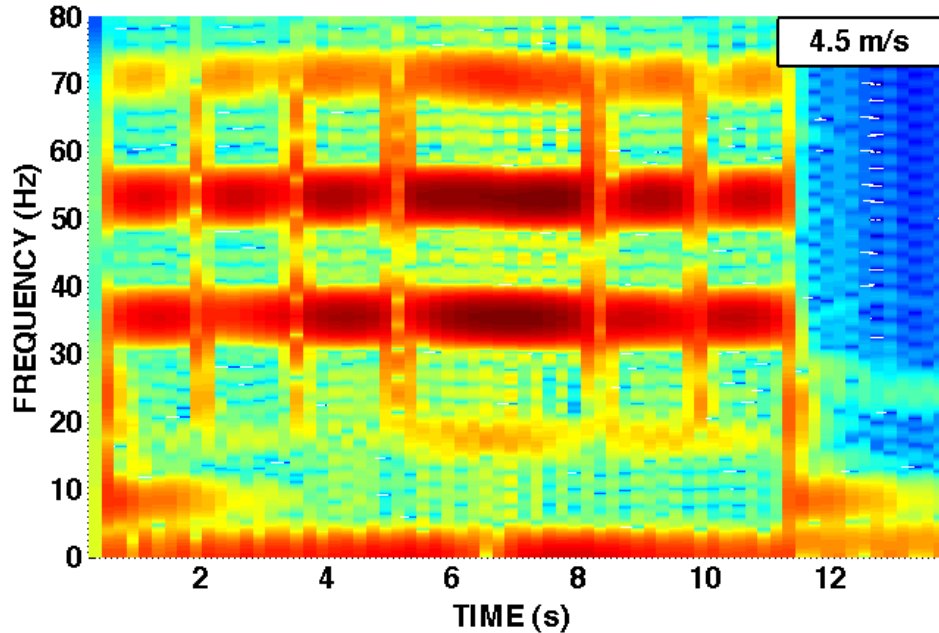
Effects of axle speed & number of axles



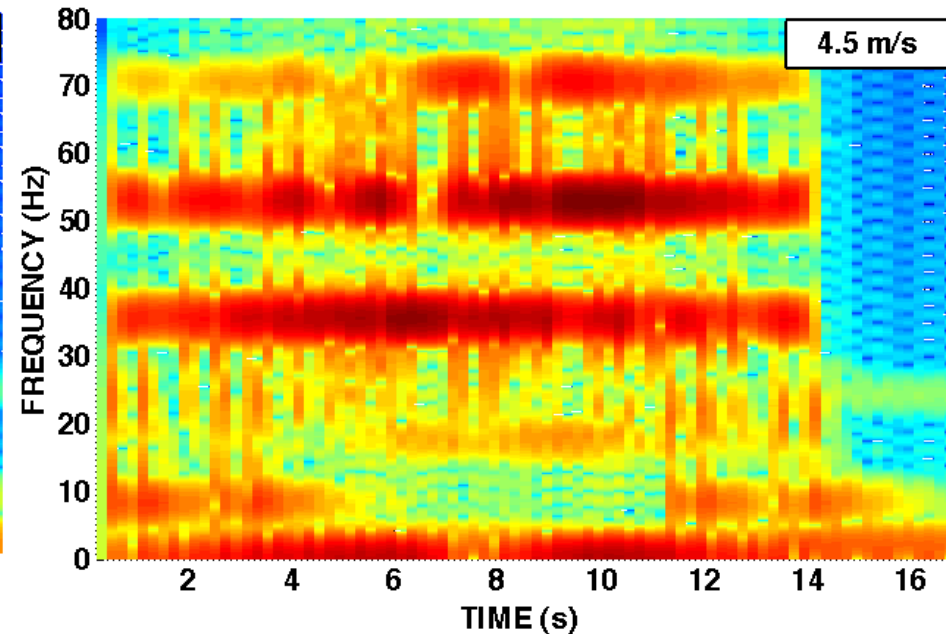
Effects of Adding Axles

Spectrograms from Particle Velocity near Center of Bridge

Single Axle



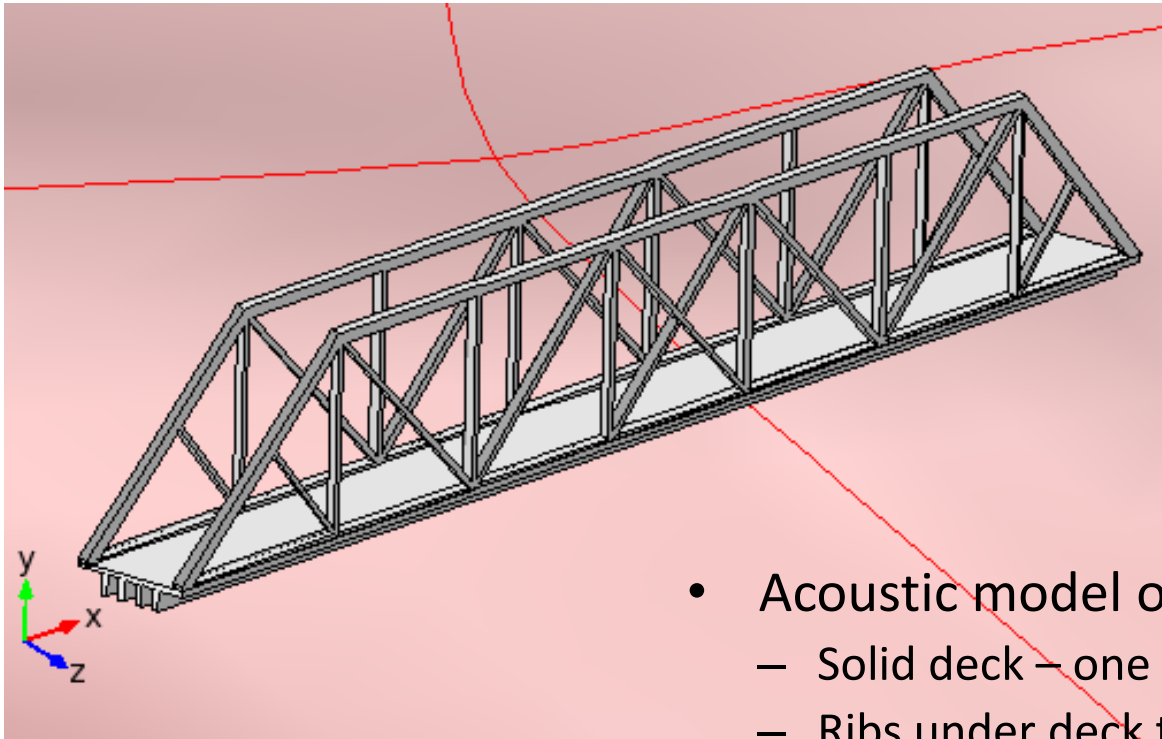
Locomotive with 4 Axles



- Differences:
 - broad-band response when axles cross Floor Beams
 - Engine takes a few seconds longer to completely leave bridge
- Similarities:
 - 2 and 8 Hz vibration as axle enters and exits bridge
 - 18, 36, 54, 72 Hz bands as axle crosses bridge



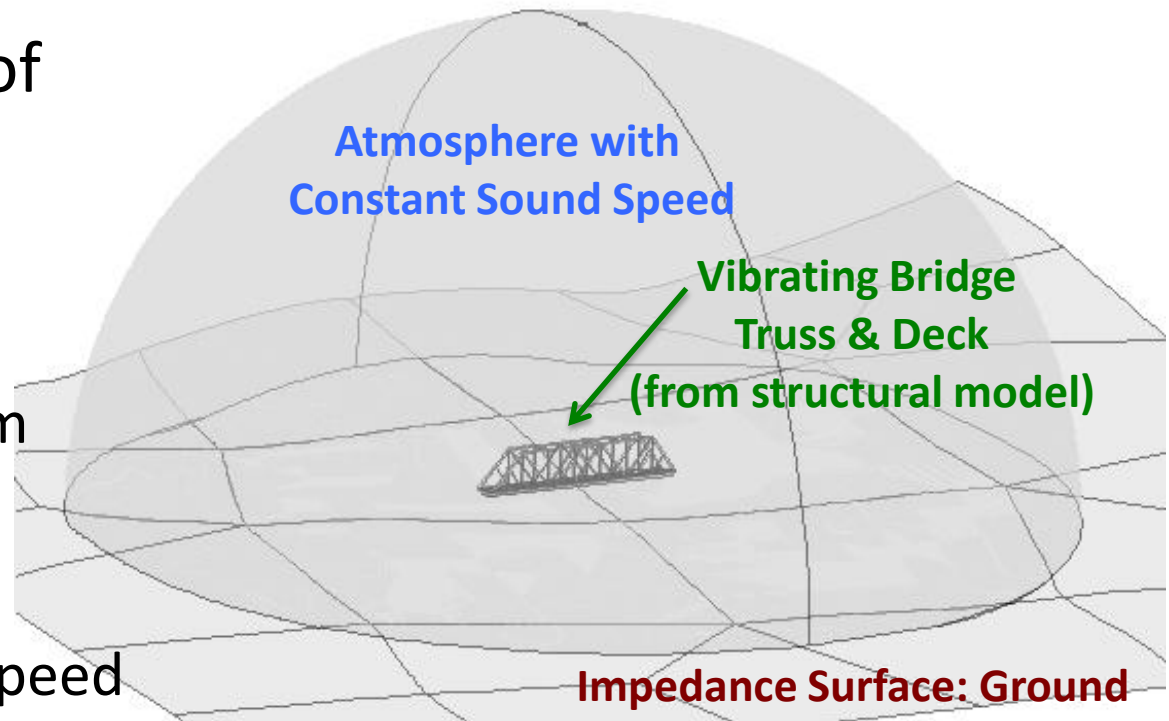
Acoustic Model of Bridge



- Structural model
 - 3-D Euler Beam elements
 - Mechanical properties: ρ , A , E , I_{xx} & I_{yy}
 - No surface area to interact with surrounding fluid
- Acoustic model of bridge
 - Solid deck – one piece
 - Ribs under deck to represent stringers
 - Truss: extruded rectangular cross-sections
 - Bridge is 'empty' volume
 - Particle acceleration specified on boundaries

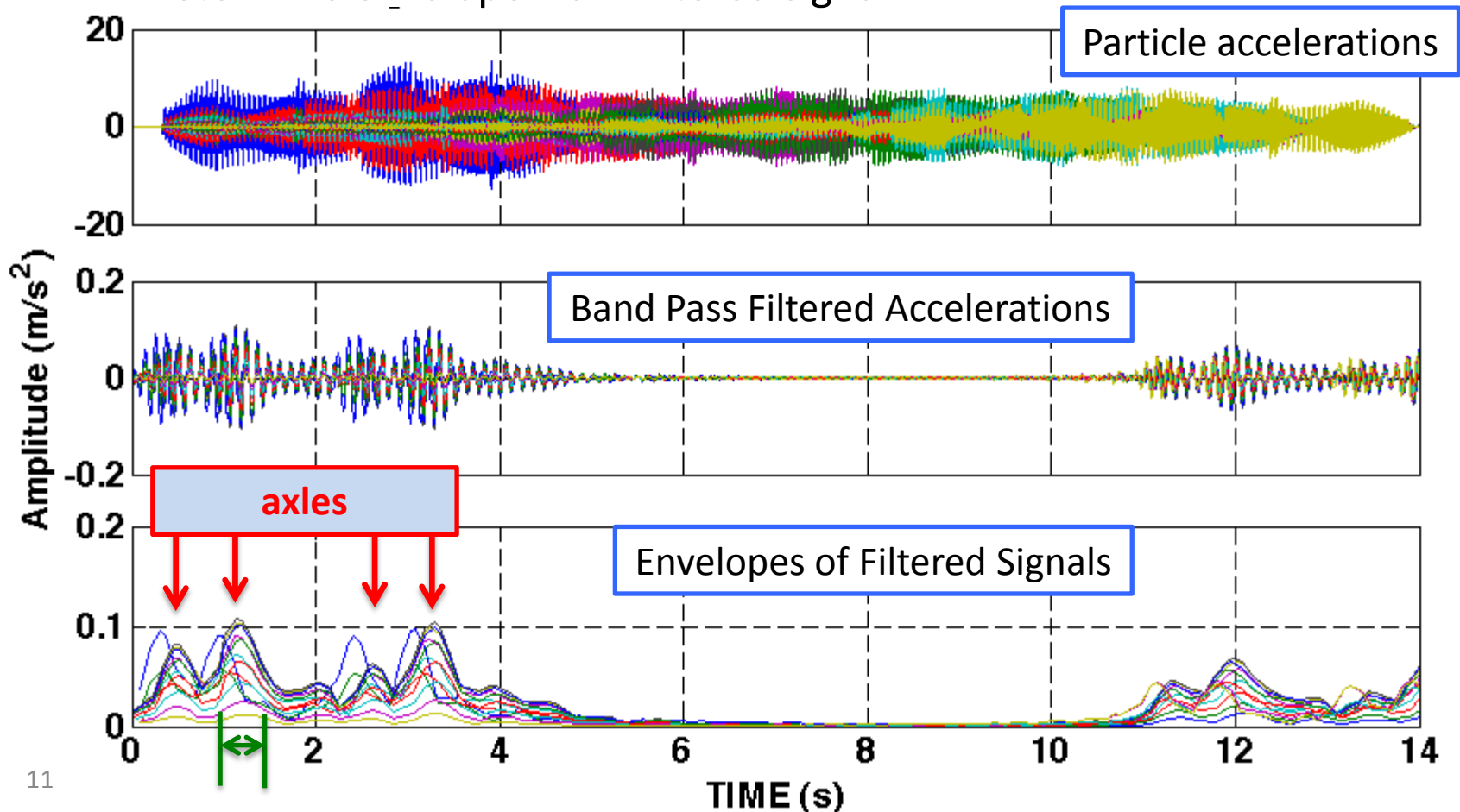
Complete Acoustic Model

- Three components
 - Acoustic model of bridge
 - Ground surface
 - From survey
 - Impedance of firm natural soil
 - Air atmosphere
 - Constant sound speed
 - Radiation BC

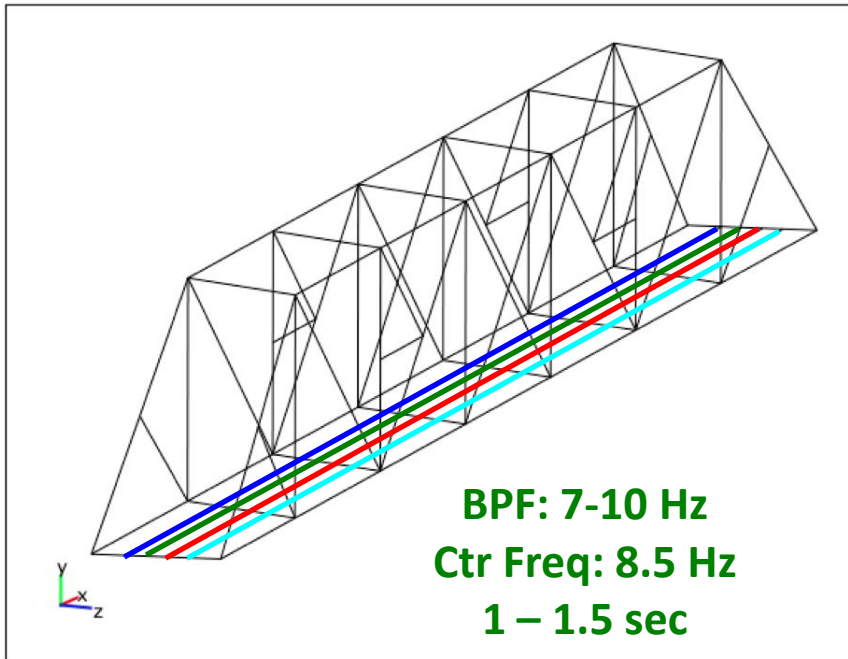


Filtered Accelerations from Structural Model

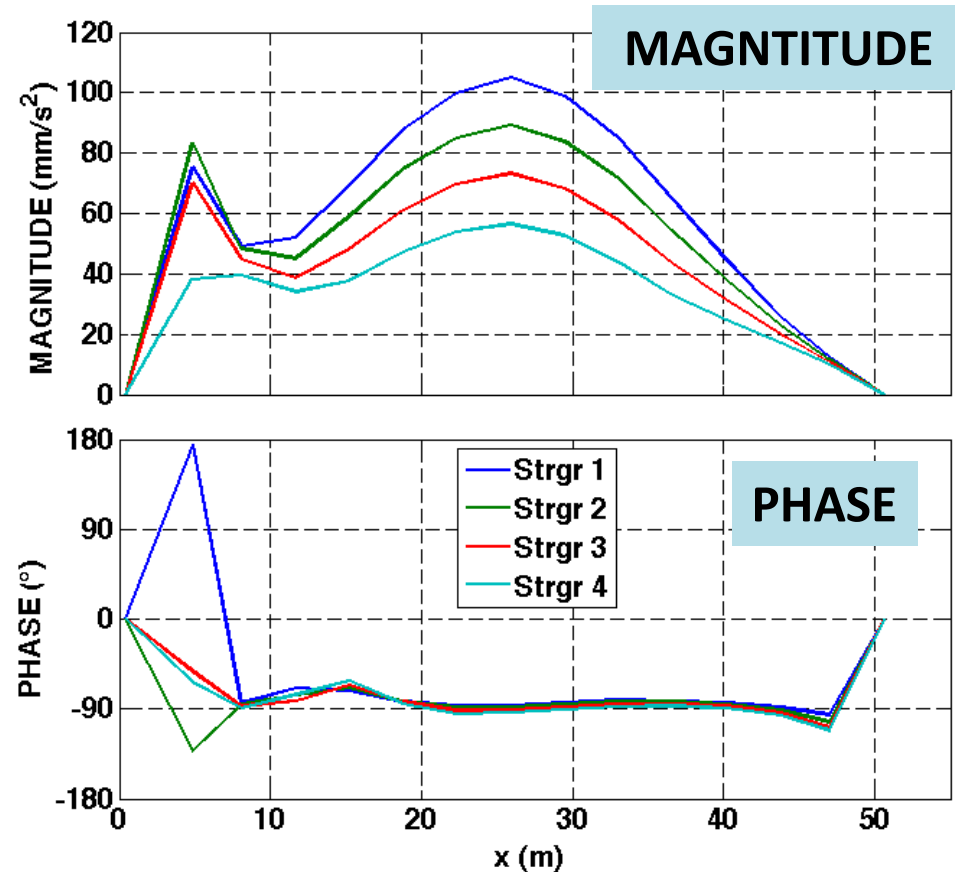
- Example: Vertical vibration of individual stringer
 - Locomotive traveling at 4.5 m/s (10 mph)
- Collect particle accelerations from points along stringer
- Bandpass filter: 7 – 10 Hz, Center frequency = 8.5 Hz
- Determine envelope from filtered signal



Acceleration Profiles

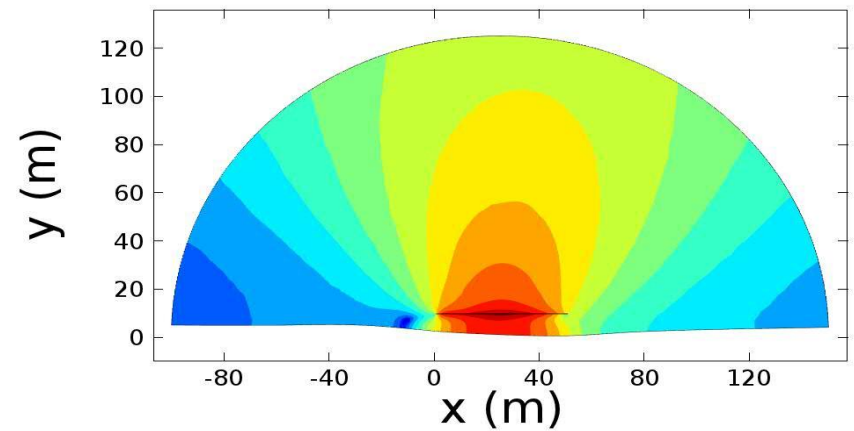
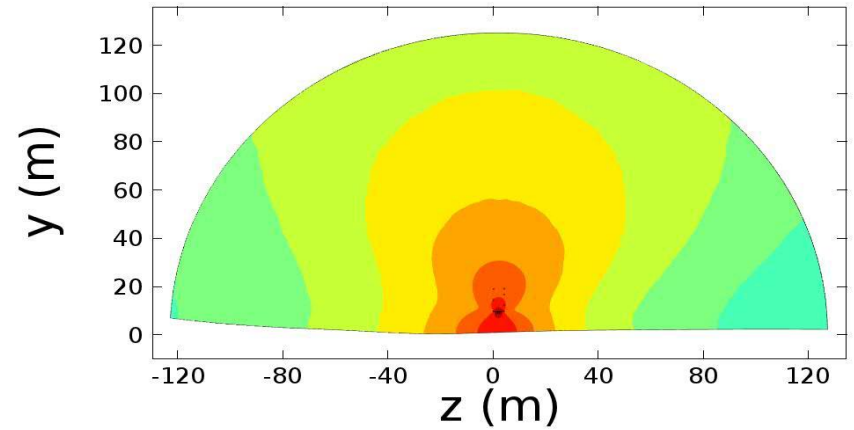
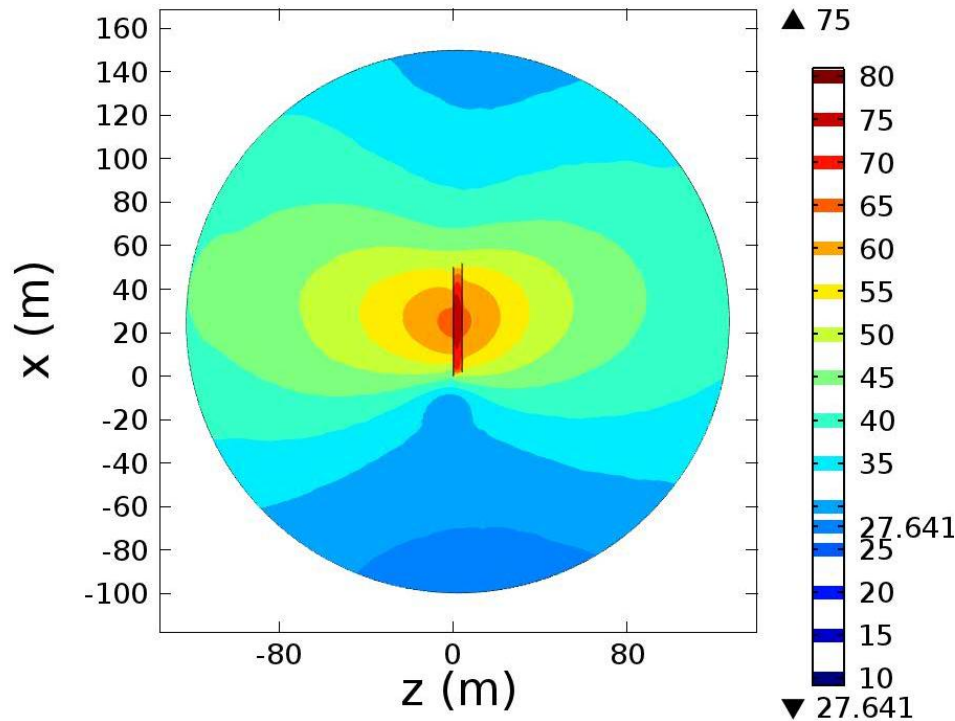


- Acceleration Profiles assembled for
 - vertical motion of bridge deck
 - horizontal motion of bridge deck
 - both components of truss motion
- The profiles are used as boundary conditions for acoustic bridge model
- Linear interpolation between points



SPL Contours, Locomotive

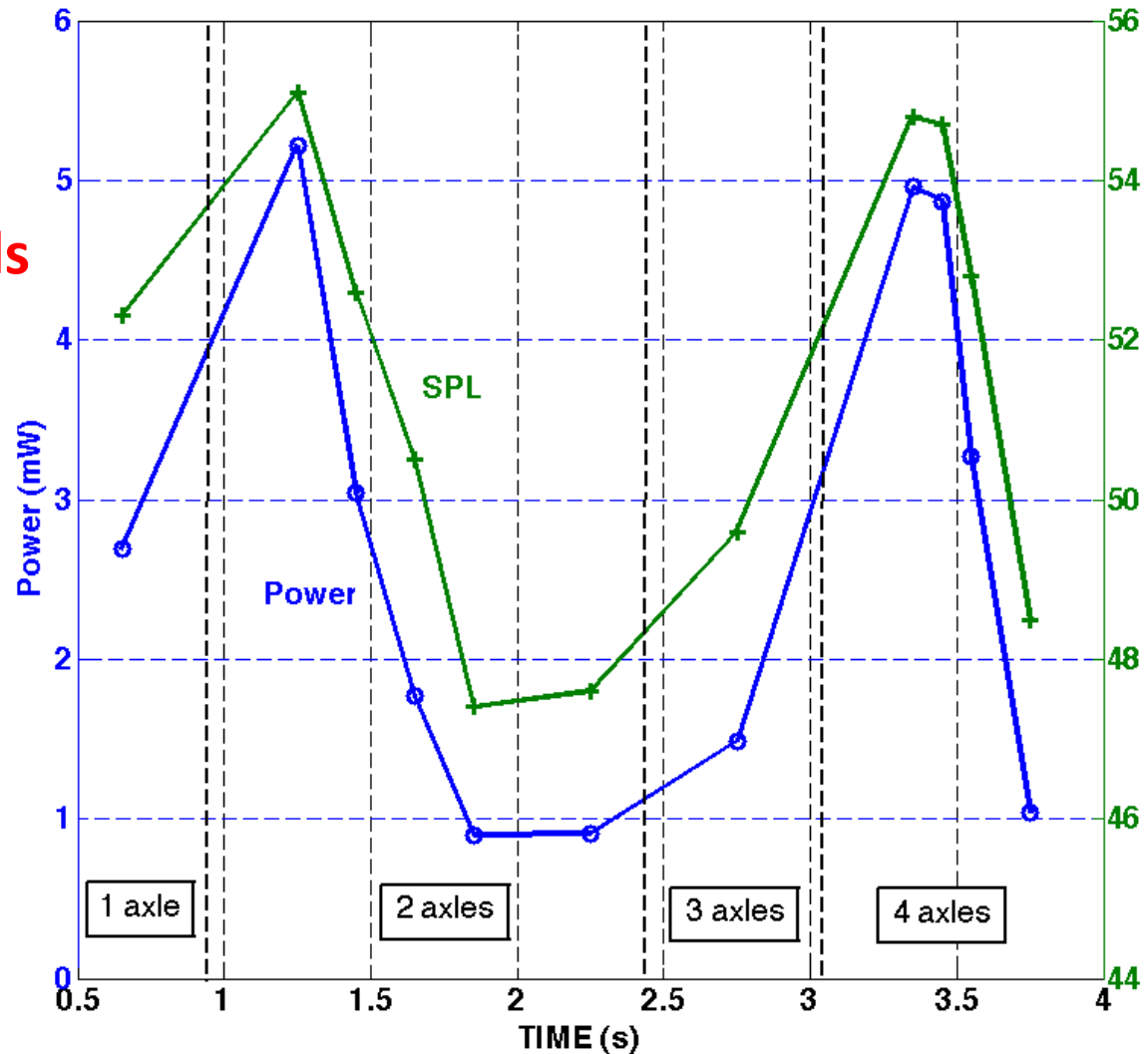
4.5 m/s; 8.5 Hz; 1-1.5 sec



Locomotive: Radiated Sound Power

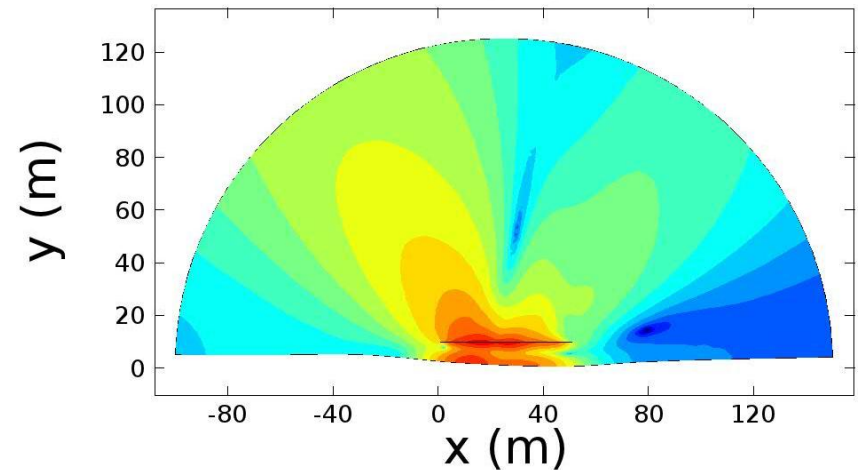
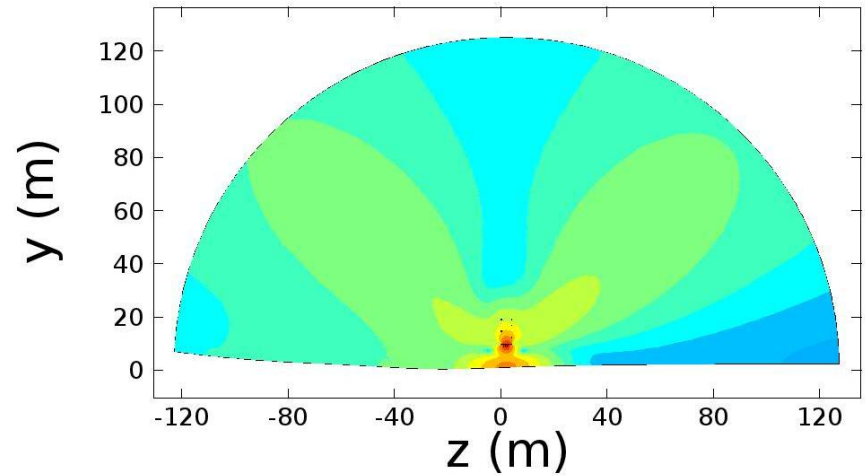
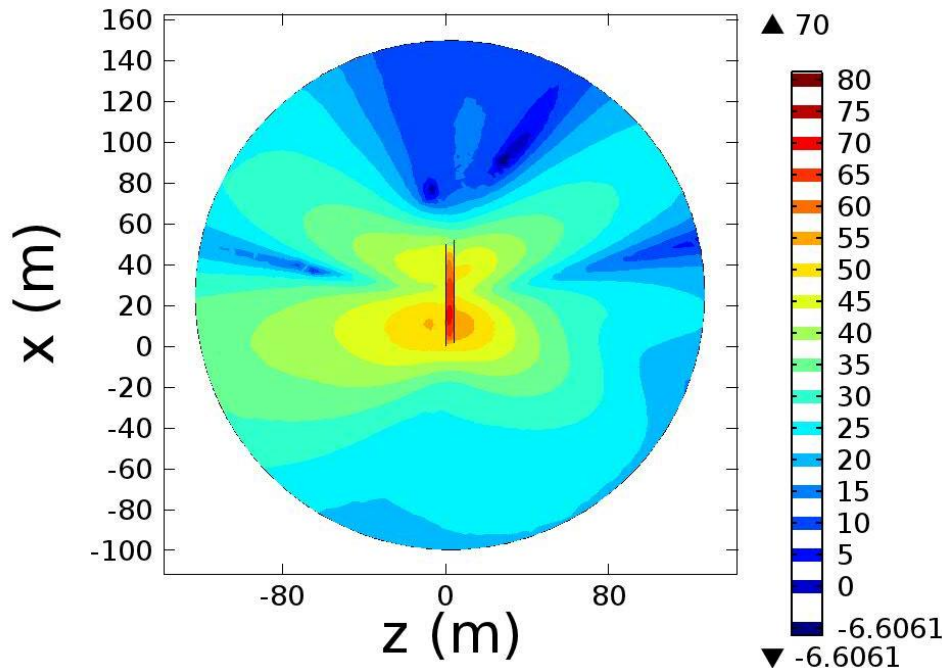
SPL at Point 90 m directly above bridge deck

- 8.5 Hz Bin
- Successive 0.5 sec intervals



SPL Contours, Locomotive

4.5 m/s; 18 Hz; 6-6.5 sec

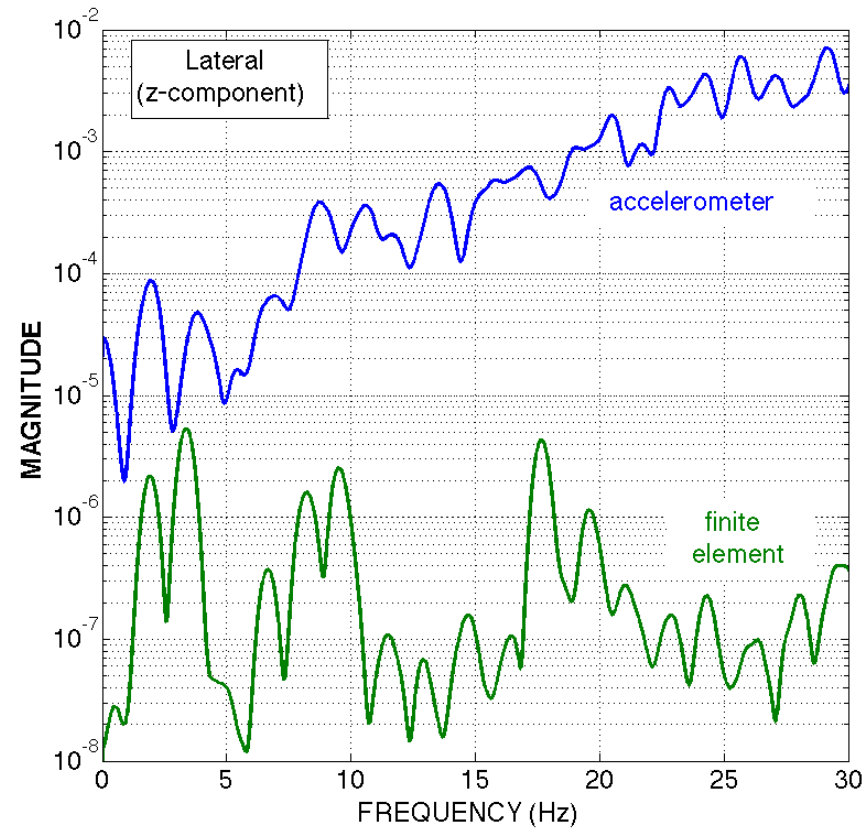
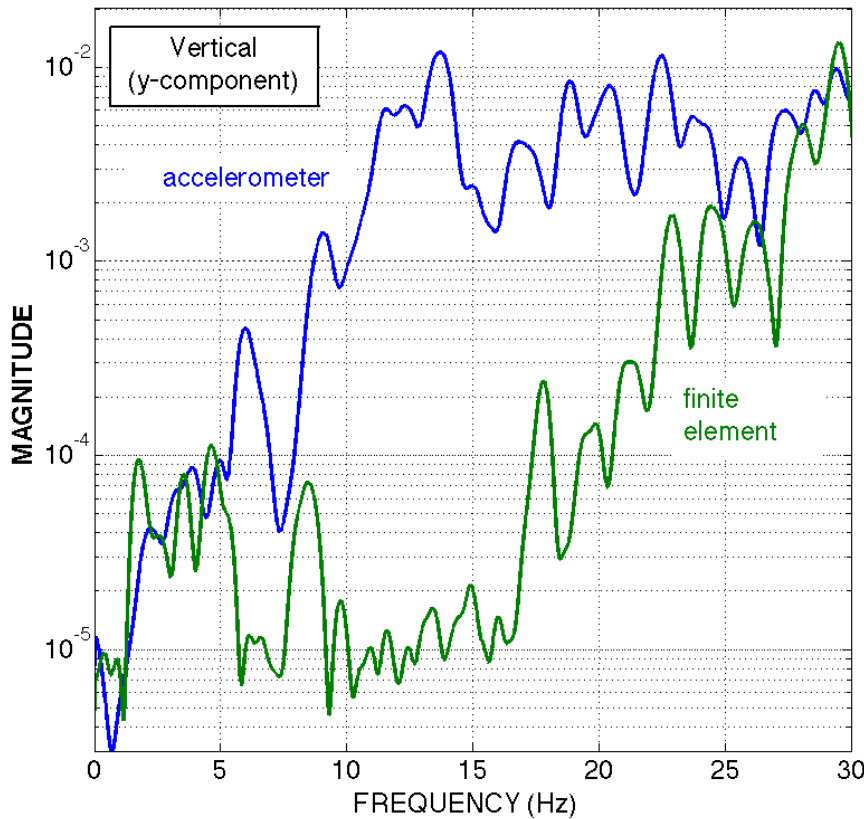


Summary & Conclusions

- Description of model
 - Euler Beam elements
 - Boundary Conditions
 - Representation of moving point load
- Structural model to determine motion of bridge deck & truss
 - Transient model
 - Single axle: simpler case for interpretation
 - Locomotive: more wheels crossing floor beams
 - Identified frequencies most likely to radiate detectable signals
- Acoustic response
 - Radiation pattern changes with frequency
 - Radiated power increases with:
 - axle weight
 - axle speed
 - number of axles
 - Vertical vibration of bridge deck - largest contributor to radiated sound
 - Largest accelerations, more surface area
 - Model does not consider porous nature of deck
 - Truss super-structure is smallest contributor
- Future efforts would include effects of vehicle suspension



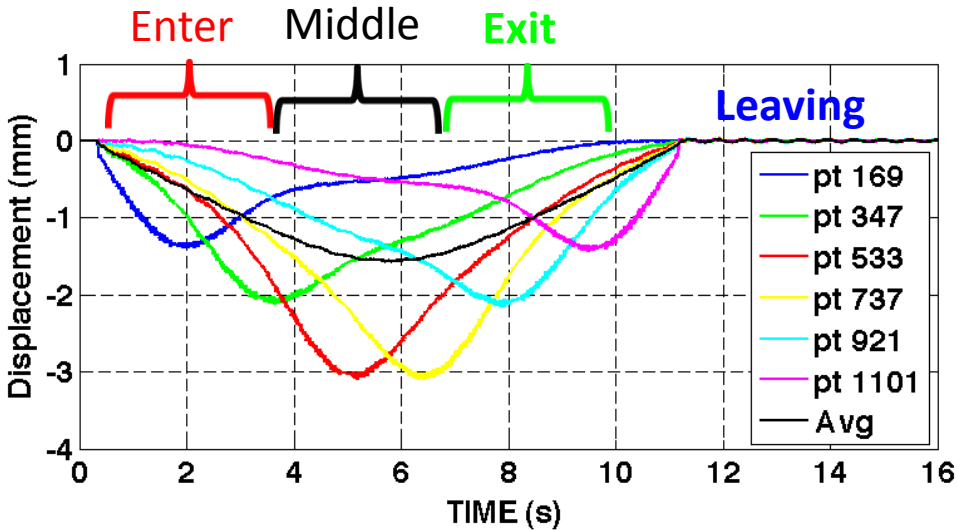
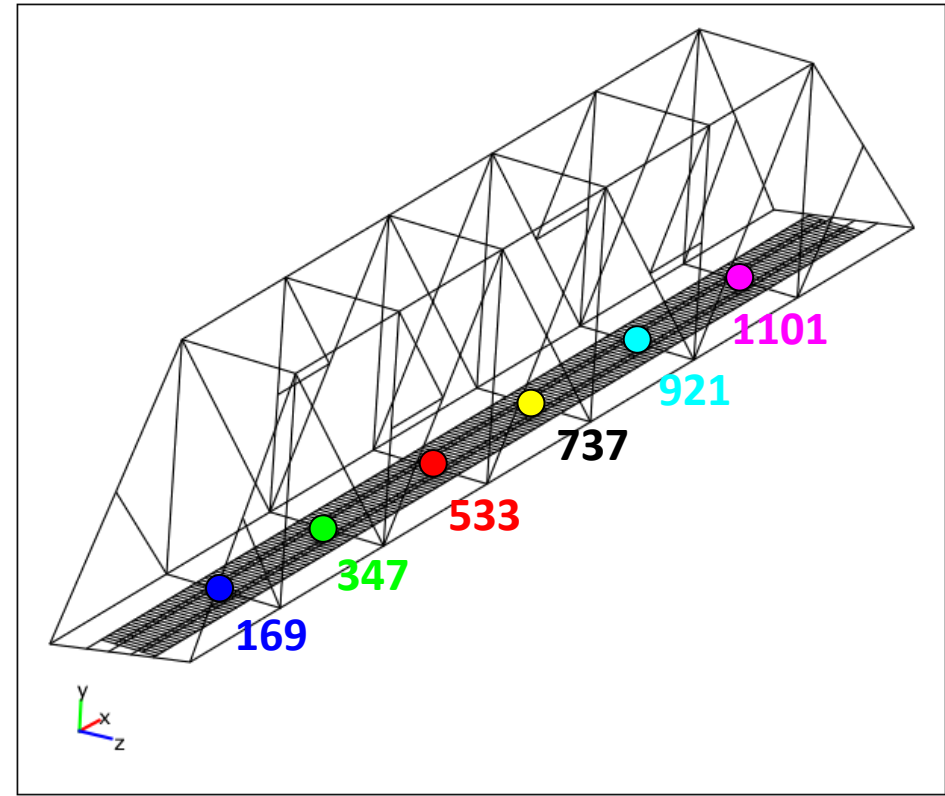
FE Comparisons with Accelerometer Data



Average Vertical Motion of Bridge Deck

- Average displacement and acceleration represents bulk motion
 - Points that vibrate in-phase will add constructively
 - Function of frequency
- Bridge deck - larger surface area
 - Acoustic radiation

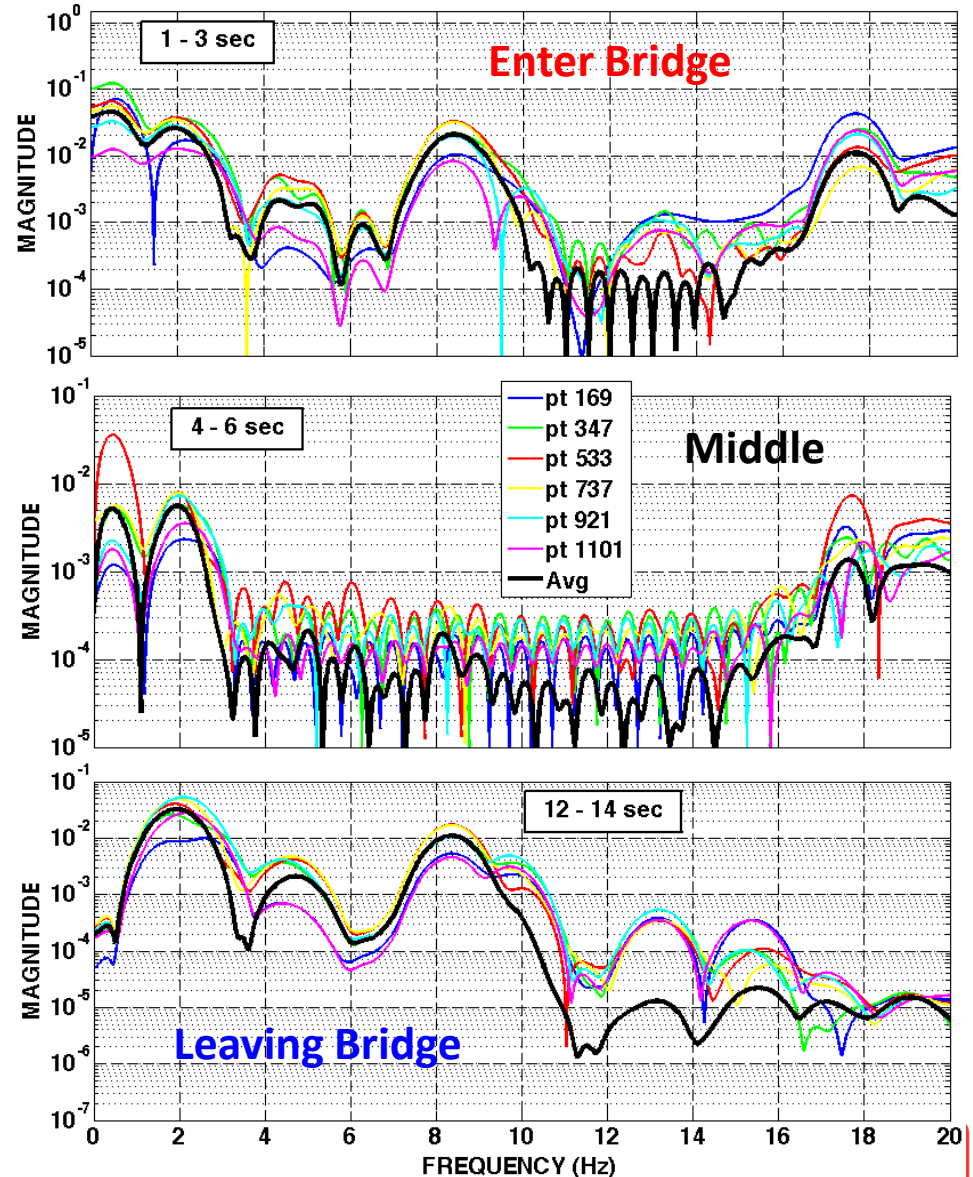
10 mph = 4.5 m/s



Frequency Spectra as Axle Crosses Bridge

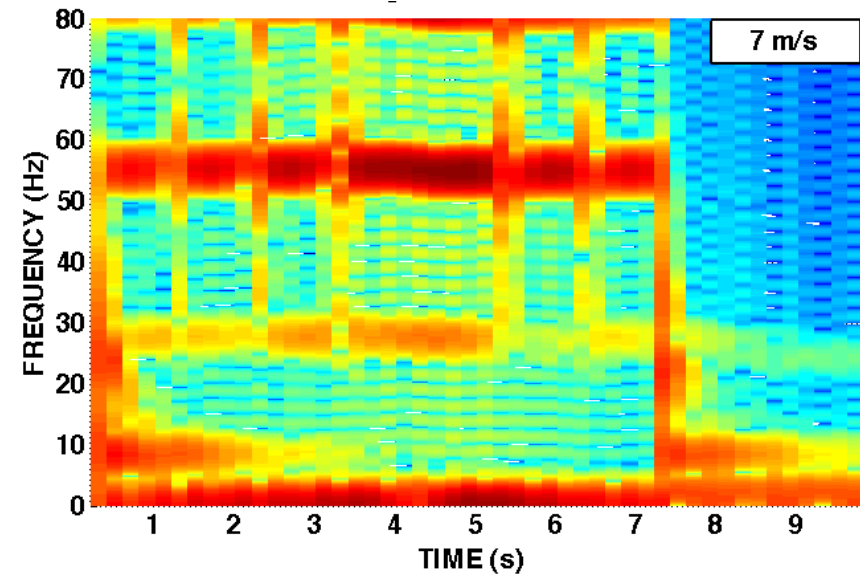
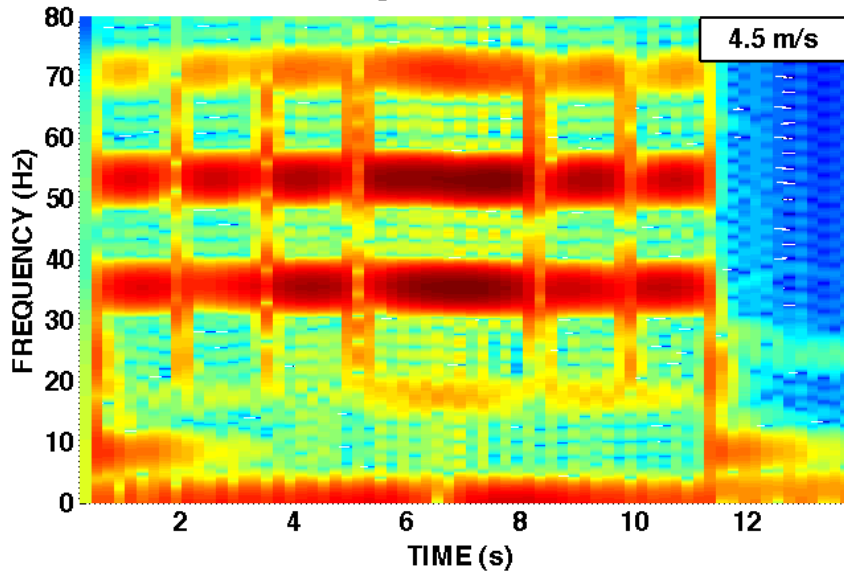
- **Enter**
 - Peaks at 2, 8, 18 Hz
- **Middle**
 - Peaks at 2 and 18 Hz
- **Leaving** - Natural frequencies
 - Peaks at 2 and 8, smaller peak at 5 Hz
 - Lost peak at 18 Hz
 - Peaks at 13 & 15 add destructively
- Large average responses indicate stringer is vibrating in phase at that frequency

10 mph = 4.5 m/s

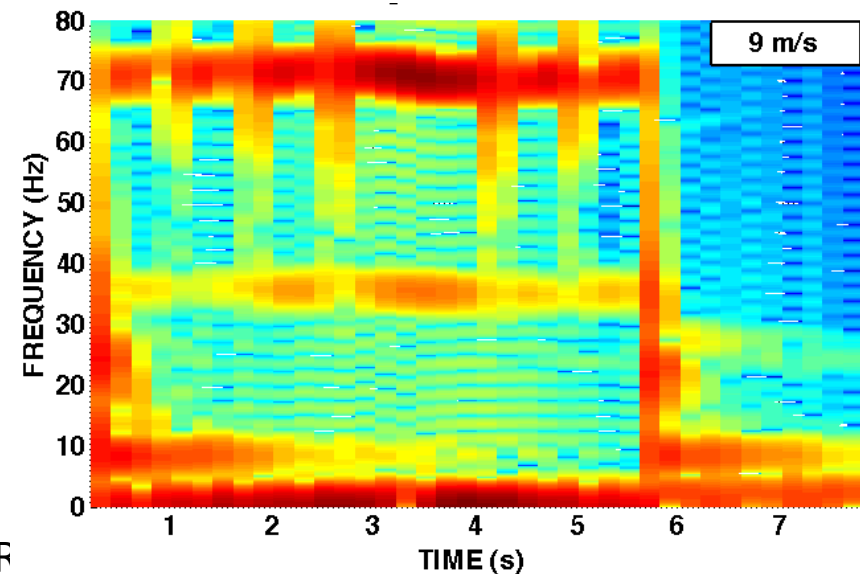


Effects of Changing Speed (single axle)

Spectrograms from Particle Velocity near Center of Bridge



- Some frequencies bands change with speed:
 - 4.5 m/s: 18, 36, 54, 72 Hz
 - 7 m/s: 27, 54 Hz
 - 9 m/s: 36, 72 Hz
- Similarities:
 - 2 and 8 Hz vibration as axle enters and exits bridge



Case Studies

Radiated Power vs. speed and number of axles

Speed (m/s)	Frequency (Hz)	SPL (dB)	Power (mW)	Interval (sec)
Single Axle				
4.5	2	21.7	7.4e-3	11-12
7	2	24.3	1.3e-2	7-8
9	2	23.9	1.2e-2	5.5-6.5
4.5	8.5	52.8	3.0	0.4-0.9
7	8.5	53.0	3.3	0.3-0.8
9	8.5	53.8	3.7	0.2-0.7
4.5	18	22.6	9.2e-2	6-6.5
Locomotive				
4.5	2	28.1	3.2e-2	13-14
4.5	8.5	55.1	5.2	1-1.5
4.5	18	32.8	0.620	6-6.5

Case Studies

Radiated Power vs. axle weight

Axle Weight (kips)	Frequency (Hz)	SPL (dB)	Power (mW)	Window (sec)
20	2	11.5	6.96e-4	11-12
40	2	17.5	2.78e-3	11-12
65	2	21.7	7.4e-3	11-12
20	8.5	42.5	0.283	0.4-0.9
40	8.5	48.5	1.13	0.4-0.9
65	8.5	52.8	2.98	0.4-0.9
20	18	12.5	8.72e-3	6-6.5
40	18	18.5	3.49e-2	6-6.5
65	18	22.7	9.21e-2	6-6.5

SPL Contours, Locomotive

4.5 m/s; 2 Hz; 13-14 sec

