Nonlinear Computational Homogenization Experiments Georgios E. Stavroulakis<sup>1</sup>, Konstadinos Giannis<sup>1</sup>, Georgios A. Drosopoulos<sup>2</sup>, Maria E. Stavroulaki<sup>1</sup> 1. Technical University of Crete, Greece; 2. Leibniz University, Hannover, Germany.

**Introduction**: A multi-scale computational homogenization method for masonry structures, is presented. COMSOL is used for the simulation of a non-linear masonry RVE, for an extensive number of loading steps and loading paths. g) Comparison of the results with direct heterogeneous macroscopic models (using ABAQUS and MARC).

#### **Results**:





Figure 1. Multi-scale computational homogenization

# **Computational Methods:**

Steps of the concept:

a) Creation of a non-linear masonry RVE with COMSOL.



**Figure 3**. Effective plastic strain of the RVE – Stress-strain diagrams



Figure 2. The masonry RVE b) Plane stress parametric analysis. c) Linear boundary conditions are the RVE loading.

d) Average  $\mathbf{u}|_{\partial V_m} = \epsilon^M \mathbf{x}$  estimation is calculated, with the subdomain integration, postprocessing capability of COMSOL.

$$\langle \boldsymbol{\epsilon} \rangle_{V_m} = \frac{1}{V_m} \int_{V_m} \boldsymbol{\epsilon}^m dV_m, \quad \langle \boldsymbol{\sigma} \rangle_{V_m} = \frac{1}{V_m} \int_{V_m} \boldsymbol{\sigma}^m dV_m$$

e) Estimation of tangent stiffness, by applying 3 test incremental loadings in each

**Figure 4**. Degradation of the strength of big macroscopic masonry walls

## **Conclusions**:

- -The method works well.
- Agreement with direct macro analysis.

### References:

1. Leftheris, B., Sapounaki, A., Stavroulaki, M.E., Stavroulakis, G.E.,

### loading path and level.

$$\begin{bmatrix} \delta \boldsymbol{\epsilon}^M \end{bmatrix} = \begin{bmatrix} \delta \boldsymbol{\epsilon}_1^M & \delta \boldsymbol{\epsilon}_2^M & \delta \boldsymbol{\epsilon}_3^M \end{bmatrix}$$
$$\begin{bmatrix} \delta \boldsymbol{\sigma}^M \end{bmatrix} = \begin{bmatrix} \delta \boldsymbol{\sigma}_1^M & \delta \boldsymbol{\sigma}_2^M & \delta \boldsymbol{\sigma}_3^M \end{bmatrix}$$

 $\begin{bmatrix} \delta \boldsymbol{\sigma}^{M} \end{bmatrix} = \mathbf{C}^{M} \begin{bmatrix} \delta \boldsymbol{\epsilon}^{M} \end{bmatrix} \Rightarrow \mathbf{C}^{M} = \begin{bmatrix} \delta \boldsymbol{\sigma}^{M} \end{bmatrix} \begin{bmatrix} \delta \boldsymbol{\epsilon}^{M} \end{bmatrix}^{-1}$ f) Incorporation of the stress-stiffness databases in computational homogenization model in MATLAB (FEM<sup>2</sup>).

Computational Mechanics for Herritage Structures, WIT Press (2006)

 Drosopoulos, G.A., Wriggers, P., Stavroulakis, G.E., Contact Analysis in Multi-Scale Computational Homogenization, CFRAC Conference proceedings, Prague (2013)

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